

University / Academy : Menoufiya University

Collge / Institute : Faculty of Electronic Engineering

Department : Industrial electronics and Control Engineering

Course Specification

1- Course basic information :		
Course Code: AC241	Course Title: Control Engineering	Academic year: Level (2) – Semester : 1
Department requirement	Teaching hours: Lecture <input type="text" value="3"/> orial <input type="text" value="2"/> <input type="text" value="-"/>	

2- Aim of the course	<ul style="list-style-type: none">○ To know the introduction and the basic knowledge of system engineering.○ Having acquired a good knowledge of performing computations of transient response, frequency response and stability.○ Analyzing the dynamics of a control system
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3- Intended Learning Outcomes:	
A- Knowledge and Understanding:	<ul style="list-style-type: none">a1) Concepts and theories of mathematics and sciences appropriate to industrial electronics and control engineering.a3) Characteristics of engineering materials related to industrial electronics and control engineering.a5) Methodologies of solving engineering problems, data collection and interpretationa6) Quality assurance systems, codes of practice and standards, health and safety requirements and environmental issues.a8) Current engineering technologies as related to industrial electronics and control engineering.a14) Basics of design and analyzing electronic engineering systems, while considering the constraints of applying inappropriate technology and the needs of commercial risk evaluation.a16) Principles of Analyzing and design of control systems with performance evaluation
B- Intellectual Skills	<ul style="list-style-type: none">b1) Select appropriate mathematical and computer-based methods for modeling and analyzing problems.b2) Select appropriate solutions for engineering problems based on analytical thinking.

	<ul style="list-style-type: none"> b3) Think in a creative and innovative way in problem solving and design. b7) Solve engineering problems, often on the basis of limited and possibly contradicting information. b11) Analyze results of numerical models and assess their limitations. b12) Create systematic and methodic approaches when dealing with new and advancing technology. b13) Develop innovative solutions for the practical industrial problems. b14) Analyze the performance of digital and analog control systems. b17) Create solutions to control systems especially to manufacturing, maintenance and interfacing problems in a creative way, taking account of industrial and commercial constraints.
C- Professional Skills	<ul style="list-style-type: none"> c1) Apply knowledge of mathematics, science, information technology, design, business context and engineering practice integrally to solve engineering problems. c2) Professionally merge the engineering knowledge, understanding, and feedback to improve design, products and/or services. c3) Create and/or re-design a process, component or system, and carry out specialized engineering designs. c4) Practice the neatness and aesthetics in design and approach. c7) Apply numerical modeling methods to engineering problems. c9) Demonstrate basic organizational and project management skills. c18) Manage field problem, identification, formulation and solution; c19) Utilize practical systems approach to design and performance evaluation; c24) Apply modern techniques, skills and engineering tools to control systems
D- General Skills	<ul style="list-style-type: none"> d2) Work in stressful environment and within constraints. d3) Communicate effectively. d5) Lead and motivate individuals. d6) Effectively manage tasks, time, and resources. d7) Search for information and engage in life-long self learning discipline. d9) Refer to relevant literatures
4- Course Contents	<p>Dynamic system model building principles. Introduction, Differential equation, Laplace transform Time response, Step and impulse responses System transient response(steady state error and dynamics) Basics of system modeling,</p>

	<p>Mathematical models, Physical models, Parameter models, Balance equations</p> <p>Application to thermal systems, chemical and mechanical process, Mechanical and electromechanical systems</p> <p>Analogy between different systems.</p> <p>Characteristics of closed loop systems</p> <p>Introduction to closed loop systems, Performance of control systems, Pole assignments.</p> <p>Stability of linear systems, Routh Hurwitz stability</p>
5- Teaching and Learning Methods	<ul style="list-style-type: none"> - Lectures - Tutorials - Research assignments
6- Teaching and Learning Methods for disable students	NA
7- Student Assessment	
a- Assessment Methods	<ul style="list-style-type: none"> - Weekly sheet exercises at class room - Quizzes - Mid term, and final exams
b- Assessment Schedule	<ul style="list-style-type: none"> - Exercise sheet/ Lab assignment : Weekly - Quizz-1: Week <u>no</u> 5 - Mid-Term exam: Week <u>no</u> 8 - Quizz-2: Week <u>no</u> - Lab exam: Week <u>no</u> - Final – term examination: Week <u>no</u> 16
c- Weighting of Assessment	<ul style="list-style-type: none"> - Class tutorial and quizzes : 16 % - Mid-term examination: 16 % - Case study and/or practical exam: ... % - Final – term examination: 68 % - Other types of assessment: % <p style="text-align: right;">Total 100 %</p>
8- List of text books and references:	
a- Course notes	There are lectures notes prepared in the form of a book authorized by the department
b- Text books	Control system engineering, Ogata
c- Recommended books	
d- Periodicals, Web sitesetc	IEEE Transaction on automatic control

Course contents - ILOs Matrix

Content Topics	Week	A- Knowledge & Understanding	B- Intellectual skills	C- Professional and practical skills	D- General and transferable skills
Dynamic system model building principles. Introduction Examples for some practical system.		a1,	b1,	c1,	d2
Differential equation		a5,	b2,	c2,	d3
Laplace transform		a6,	b3,	c7,	d2
Time response. Step and impulse responses		a8,	b7,	c3,	d3
System transient response(steady state error and dynamics)		a3,	b12,	c9,	d5
Basics of system modeling, Mathematical models. Physical models.		a1,	b1,	c24	
Parameter models. Balance equations		a14,	b11,	c1,	d2
Application to thermal systems. chemical and mechanical process		a16,	b13,	c9,	d5
Mechanical and electromechanical systems		a14,	b14,		d3
Analogy between different systems.		a5,	b17,	c18,	d5
Examples of practical systems			b17,		d6
Characteristics of closed loop systems Introduction to closed loop systems Performance of control systems		a3,	b1,	c4,	d6

Pole assignments.		a8,	b12,	c19,	d7
Routh Hurwitz stability		a3,		c4	,d9

Course coordinator: Prof. Abdelazim Sobieh Ibrahim

Head of Department: Prof. Mohamed A. Fkirin

Date: / /